



The 30th International Conference on
Technologies and Applications of Artificial Intelligence

December 13-14, 2025

Synergistic Pseudo-Labeling: Harmonizing Heterogeneous Datasets with a Foundation Model

Jing-Qiao Chen¹, Cheng-Hsueh Hu¹, Kai-Jun Liang¹

Chien-Yao Wang², Yi-Ting Huang¹

1. Department of Electrical Engineering, National Taiwan University
of Science and Technology, Taipei, Taiwan

2. Institute of Information Science, Academia Sinica, Taipei, Taiwan

Paper ID: 170

Outline

- Introduction
- Related Work
- Background
- Method
- Experimental Methodology
- Conclusion
- Reference

Introduction

Challenge - Introduction

- Challenge 1: High Annotation Cost
 - Semantic segmentation relies heavily on large-scale, pixel-level labeled data.
 - Mitigation: Using existing heterogeneous datasets.
- Challenge 2: Heterogeneous Label Spaces
 - Root Cause: Inconsistent class taxonomies and varying levels of granularity.
 - Our Solution: Proposing the **Integrated Pseudo-Labeling (IPL) Pipeline**.

Main Contribution - Introduction

- **New Framework:** Proposed a new, effective framework for automating pixel-level labeling and addressing data scarcity with minimal manual effort.
- **Intelligent Aggregation:** Designed a new weighted voting mechanism that leverages both class-specific expertise and general model reliability.
- **Preservation Strategy:** Introduced a rule-based integration strategy that preserves the quality of original ground-truth labels.



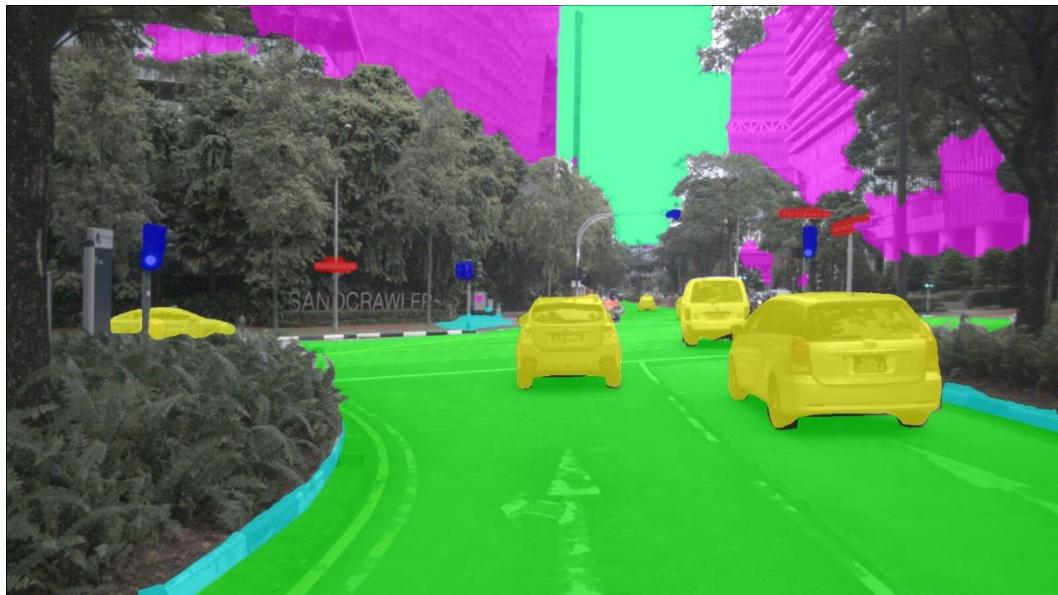
nuImages ground truth



EOV-Seg Prediction



OpenSeed Prediction



Our Full Method

Related Work

Related Work

- Pseudo-Labeling
 - Focuses on adaptation within a **unified label taxonomy**.[7]
- Traditional Ensemble Methods
 - Relies on **simple majority voting**; fails to capture models' **specific class expertise**. [4]
- Multi-Dataset Learning
 - A central challenge in this area is **resolving conflicts in datasets** with heterogeneous label spaces. (e.g., Cityscapes: person; nuImages: adult, child, ...) [3][2]

Related Work

- Label Harmonization Framework
 - **Explicitly resolves heterogeneous label conflicts** across multiple datasets.
- Performance-Aware Weighted Voting
 - Intelligently balances "**Specific Confidence**" with "**General Reliability**".
- Model-Agnostic Post-Processing
 - **High efficiency and low cost**, integrating predictions directly via rule-based policies.

Background

Datasets - Background

- Datasets Utilized
 - We involve mainstream semantic segmentation datasets, notably nuImages and BDD100K. [10]
- Key Relationship
 - Datasets like Cityscapes, KITTI, and BDD100K share a common set of 19 evaluation classes. [3][5][10]
- R_{manual} (Class Mapping Rules)
 - We define these rules to formalize the parent-child and conceptual overlap relationships.

Datasets - Background

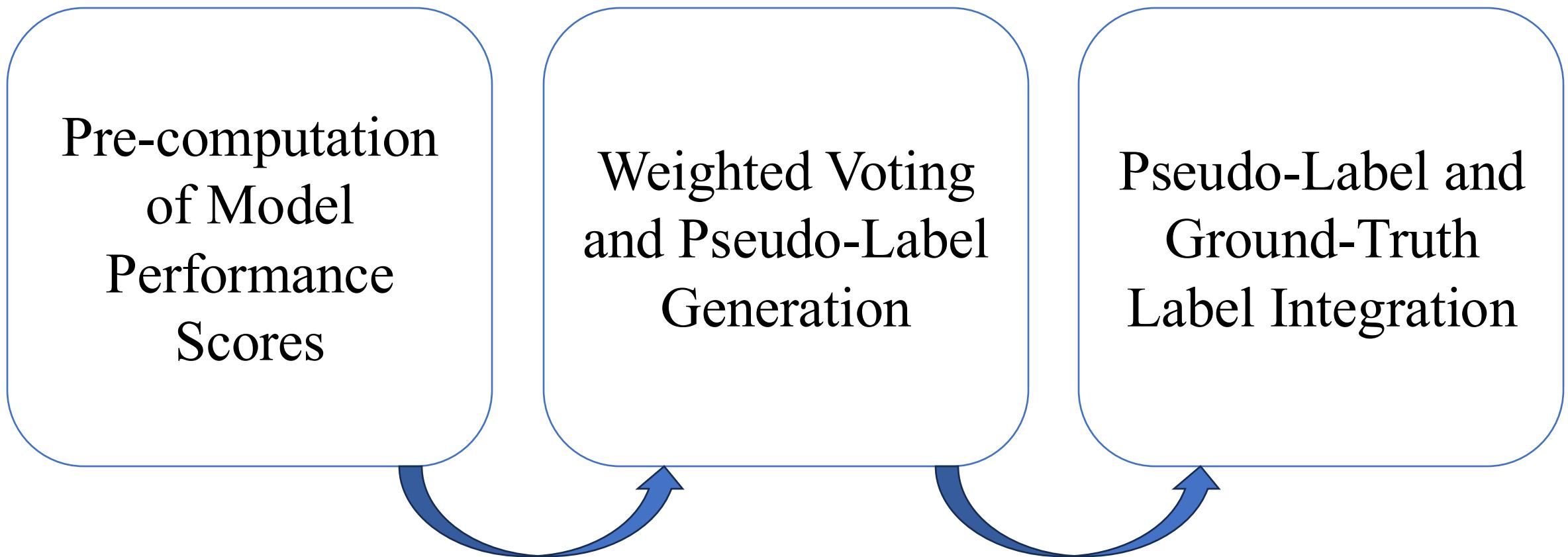
| Cityscapes | nuImages | Relationship |
|------------|---|--|
| person | human.pedestrian.adult human.pedestrian.child human.pedestrian.construction_worker human.pedestrian.personal_mobility human.pedestrian.police_officer human.pedestrian.stroller human.pedestrian.wheelchair | Parent-Child (nuImages is more granular) |
| rider | (No direct equivalent) | Unique to Cityscapes |
| car | vehicle.car vehicle.construction vehicle.emergency.ambulance vehicle.emergency.police | Parent-Child (nuImages is more granular) |
| bus | vehicle.bus.rigid, vehicle.bus.bendy | Parent-Child |
| truck | vehicle.truck | Direct Mapping |
| trailer | vehicle.trailer | Direct Mapping |
| caravan | (No direct equivalent) | Unique to Cityscapes |
| motorcycle | vehicle.motorcycle | Direct Mapping |
| bicycle | vehicle.bicycle | Direct Mapping |
| train | (No direct equivalent) | Unique to Cityscapes |

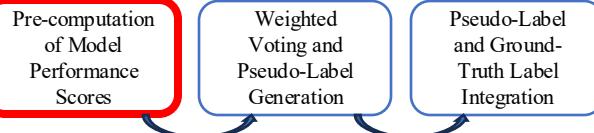
Foundation Models - Background

- **OpenSeed**
 - It offers strong generalization for open-vocabulary tasks.
 - It is suitable for multi-dataset integration.
- **EOV-Seg**
 - It provides high efficiency with reduced computational cost.
 - It is ideal for fast, high-quality pseudo-label generation in constrained-category settings

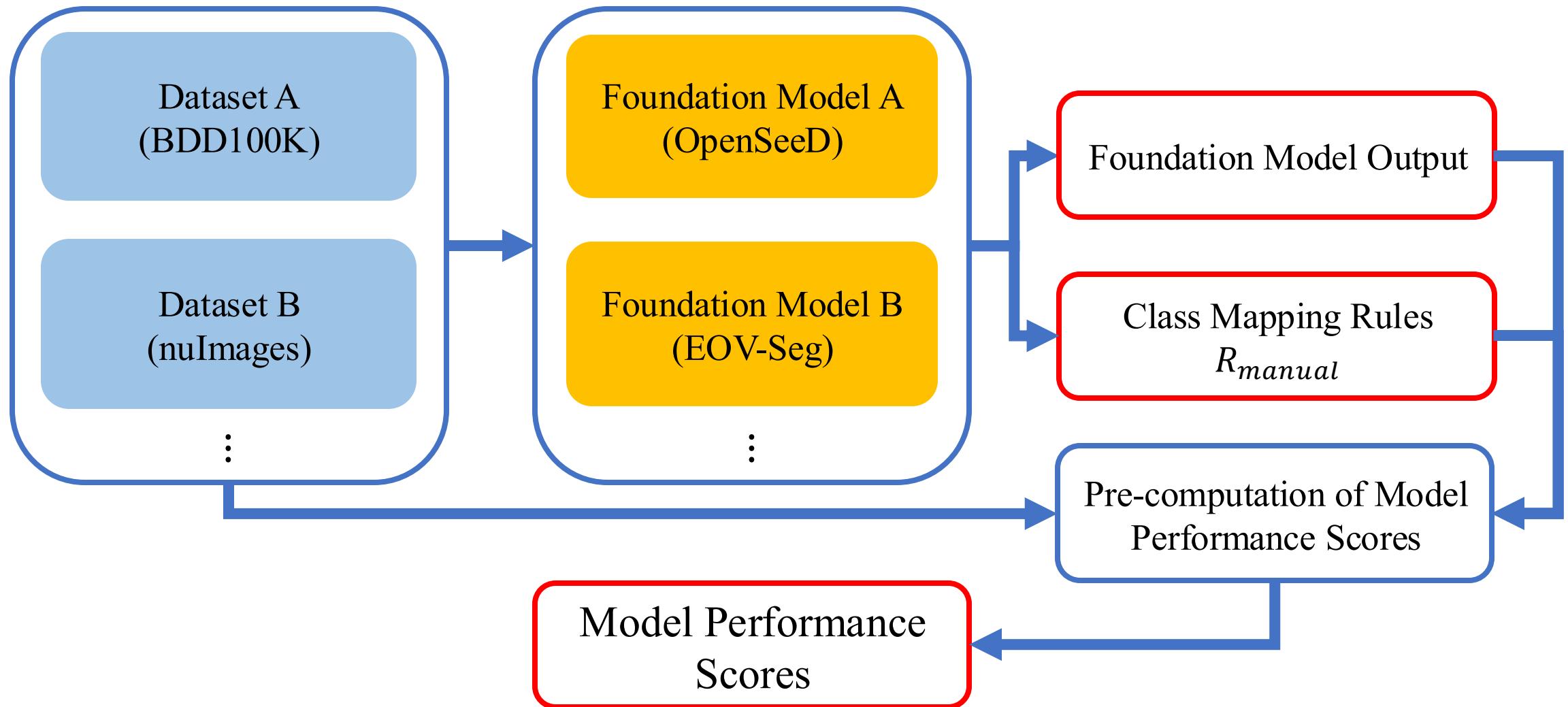
Method

Integrated Pseudo-Labeling (IPL) Pipeline





Pre-computation - Implementation



Pre-computation of Model Performance Scores

- Goal:
 - Establish a Performance-Aware weighting basis for the subsequent voting scheme.
- Class Variance:
 - A single model exhibits varying performance across different semantic classes (e.g., better at detecting car than tree).
- Dataset Variance:
 - The same class may have different reliability scores when predicted by models trained on heterogeneous datasets.

Weighted Voting and Pseudo-Label Generation

$$W_{Model,specific} = F1_{specific} + F1_{avg}$$

$$F1_{specific}$$

Define: The F1-score of the specific class currently being voted on in another dataset.

Function: Rewards the model for its domain expertise.

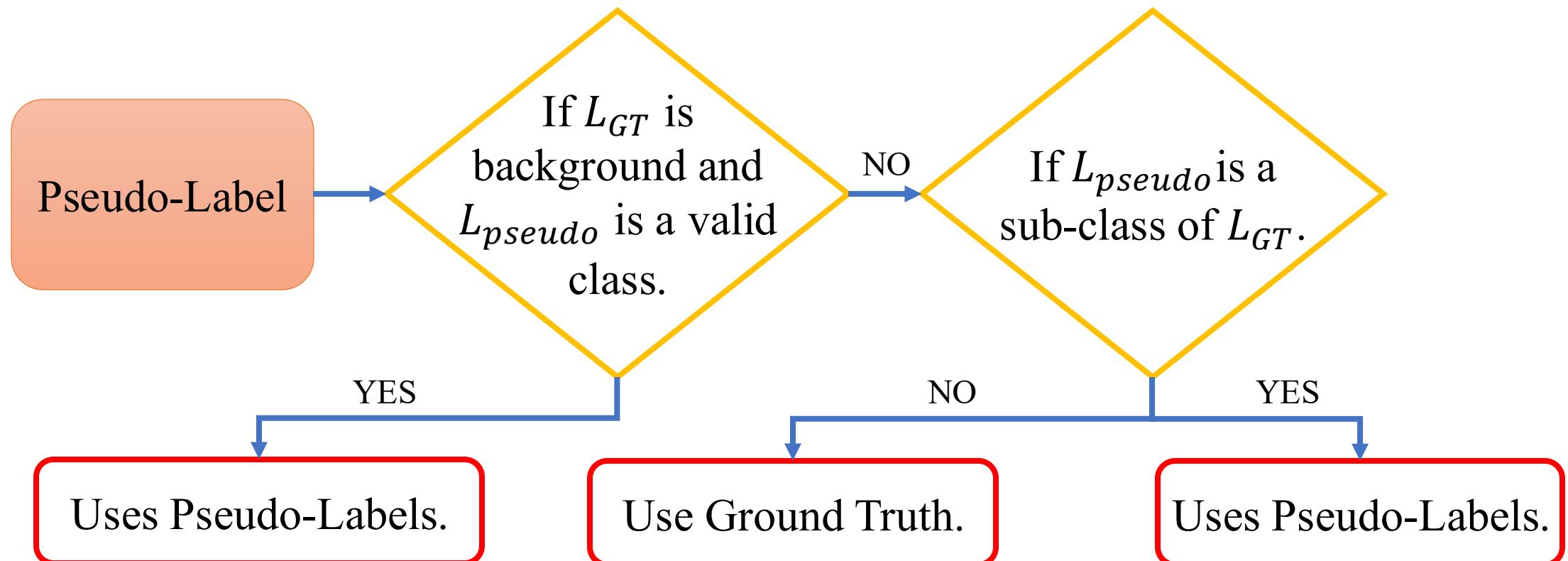
$$F1_{avg}$$

Define: The average F1-score of the shared class in this dataset.

Function: Ensures stable baseline quality.

Synergistic Balance: This way synergistically balances the model's overall stability with its specific competence, resulting in higher quality pseudo-labels .

Pseudo-Label and Ground-Truth Label Integration



To expand and **fill in missing annotations** in the original data.

Ensures the **integrity** of the **original high-quality** labels is maintained.

Uses pre-defined R_{manual} to **retain finer granularity** in the final label map.

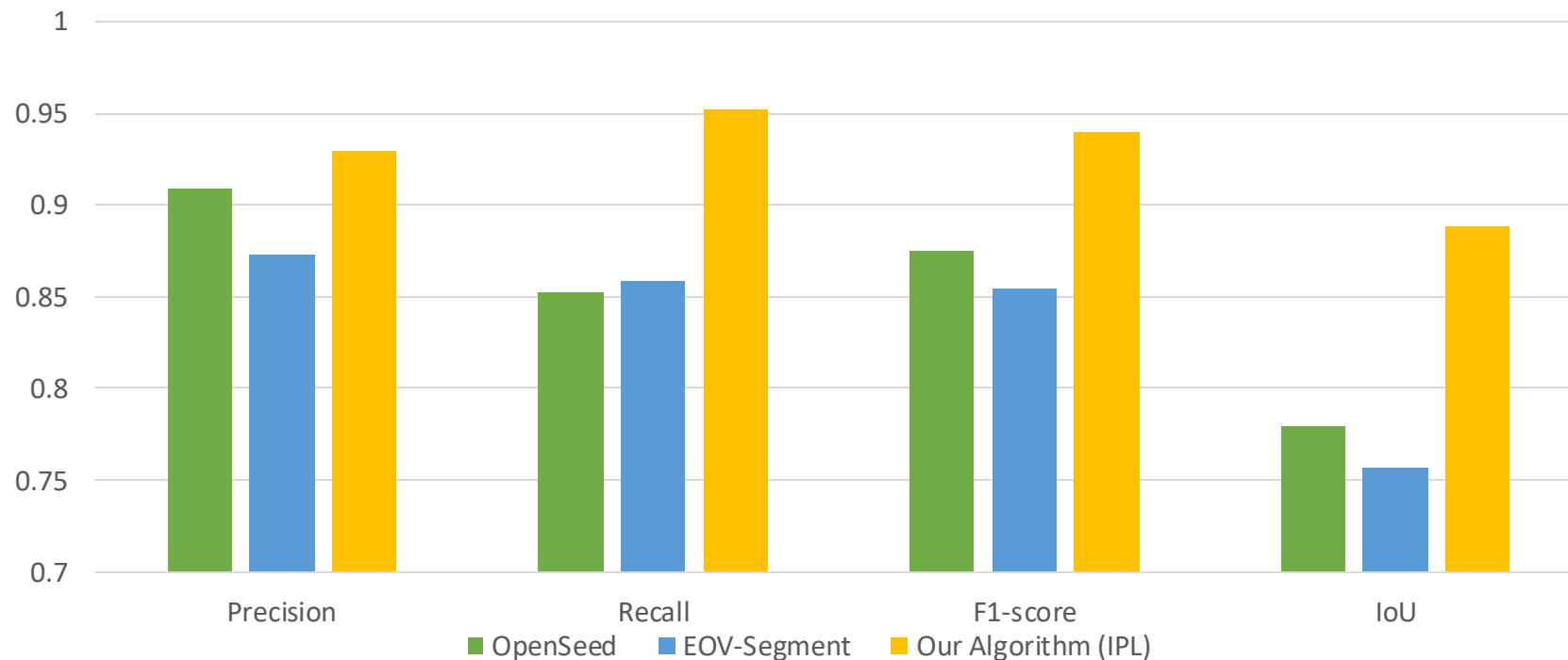
Experimental Methodology

Experimental Methodology

- Goal: Complement the categories of nuImages to align them with other mainstream datasets.
- Assume that the nuImages dataset lacks annotations for the three categories, "bicycle," "car," and "bus".
- Use our algorithm to generate pseudo-labels for these missing categories.

Experimental Results

| Category | OpenSeeD | | | | EOV-Segment | | | | Our Algorithm (IPL) | | | |
|----------------|---------------|--------|----------|--------|---------------|--------|---------------|---------------|---------------------|---------------|---------------|---------------|
| | Precision | Recall | F1-score | IoU | Precision | Recall | F1-score | IoU | Precision | Recall | F1-score | IoU |
| bicycle | 0.9392 | 0.7599 | 0.8399 | 0.7243 | 0.9284 | 0.7393 | 0.8231 | 0.7001 | 0.9364 | 0.9077 | 0.9217 | 0.8550 |
| bus | 0.8291 | 0.9327 | 0.8779 | 0.7823 | 0.9328 | 0.9317 | 0.9323 | 0.8731 | 0.8725 | 0.9664 | 0.9170 | 0.8470 |
| car | 0.9580 | 0.8643 | 0.9086 | 0.8324 | 0.7573 | 0.9053 | 0.8068 | 0.6965 | 0.9807 | 0.9829 | 0.9818 | 0.9642 |
| Average | 0.9088 | 0.8523 | 0.8755 | 0.7797 | 0.8728 | 0.8588 | 0.8541 | 0.7566 | 0.9297 | 0.9523 | 0.9402 | 0.8887 |



Ablation Study - Two Step

To further dissect the effectiveness of our proposed IPL pipeline, we conduct an ablation study to analyze the individual contributions of our two core components:

1. The weighted voting scheme.
2. The ground-truth (GT) integration policy.

| Method | bicycle | bus | car | Avg. IoU |
|--------------------------|---------------|---------------|---------------|---------------|
| OpenSeeD (Baseline) | 0.7243 | 0.7823 | 0.8324 | 0.7797 |
| EOV-Segment (Baseline) | 0.7001 | 0.8731 | 0.6965 | 0.7566 |
| IPL (Voting Only) | 0.8288 | 0.8368 | 0.7484 | 0.8047 |
| IPL (Full Method) | 0.8549 | 0.8469 | 0.9642 | 0.8887 |

Ablation Study - Metric

To validate the selection of the core metric (F1-score, Precision, or Recall) for our performance-aware weighted voting scheme.

The F1-score-based Weight consistently yields superior performance across all categories, achieving the highest Average IoU (0.8047).

| Voting Weight Metric | bicycle | bus | car | Avg. IoU |
|------------------------|---------------|---------------|---------------|---------------|
| Precision-based Weight | 0.8237 | 0.8324 | 0.7489 | 0.8017 |
| Recall-based Weight | 0.8194 | 0.8015 | 0.7425 | 0.7878 |
| F1-score-based Weight | 0.8288 | 0.8368 | 0.7484 | 0.8047 |

Ablation Study - Metric

To validate the selection of the core metric ($F1_{specific} + F1_{avg}$, $F1_{specific}$ only, or $F1_{avg}$ only) for our performance-aware weighted voting scheme.

The $F1_{specific} + F1_{avg}$ Weight consistently yields superior performance across all categories, achieving the highest Average IoU (0.8047).

| Voting Weight Component | bicycle | bus | car | Avg. IoU |
|--|---------------|---------------|---------------|---------------|
| Specialist Competence ($F1_{specific}$ only) | 0.8162 | 0.8368 | 0.7489 | 0.8006 |
| Generalist Reliability ($F1_{avg}$ only) | 0.8194 | 0.8012 | 0.7443 | 0.7883 |
| Balanced Combination ($F1_{specific} + F1_{avg}$) | 0.8288 | 0.8368 | 0.7484 | 0.8047 |

Conclusion

Core Conclusion

- **Successfully Addressed Label Inconsistency:** Introduced the IPL pipeline, resolving the critical challenge of harmonizing heterogeneous semantic segmentation datasets.
- **Automated High-Quality Pseudo-Labeling:** Achieved significantly higher quality pseudo-labels than individual models.
- **Validated Components:** Ablation studies confirmed that both **Weighted Voting** and **Rule-Based Integration** are crucial for superior performance.

Main Contribution

- **New Framework:** Proposed a new, effective framework for automating pixel-level labeling and addressing data scarcity with minimal manual effort.
- **Intelligent Aggregation:** Designed a new weighted voting mechanism that leverages both class-specific expertise and general model reliability.
- **Preservation Strategy:** Introduced a rule-based integration strategy that preserves the quality of original ground-truth labels.

Future Work

- **Adaptive Rule Derivation:** Explore using Large Language Models (LLMs) to automatically construct semantic hierarchies between class labels .
- **Task Extension:** Extend the *IPL* framework to other dense prediction tasks, such as Instance Segmentation or Depth Estimation, to validate its versatility.

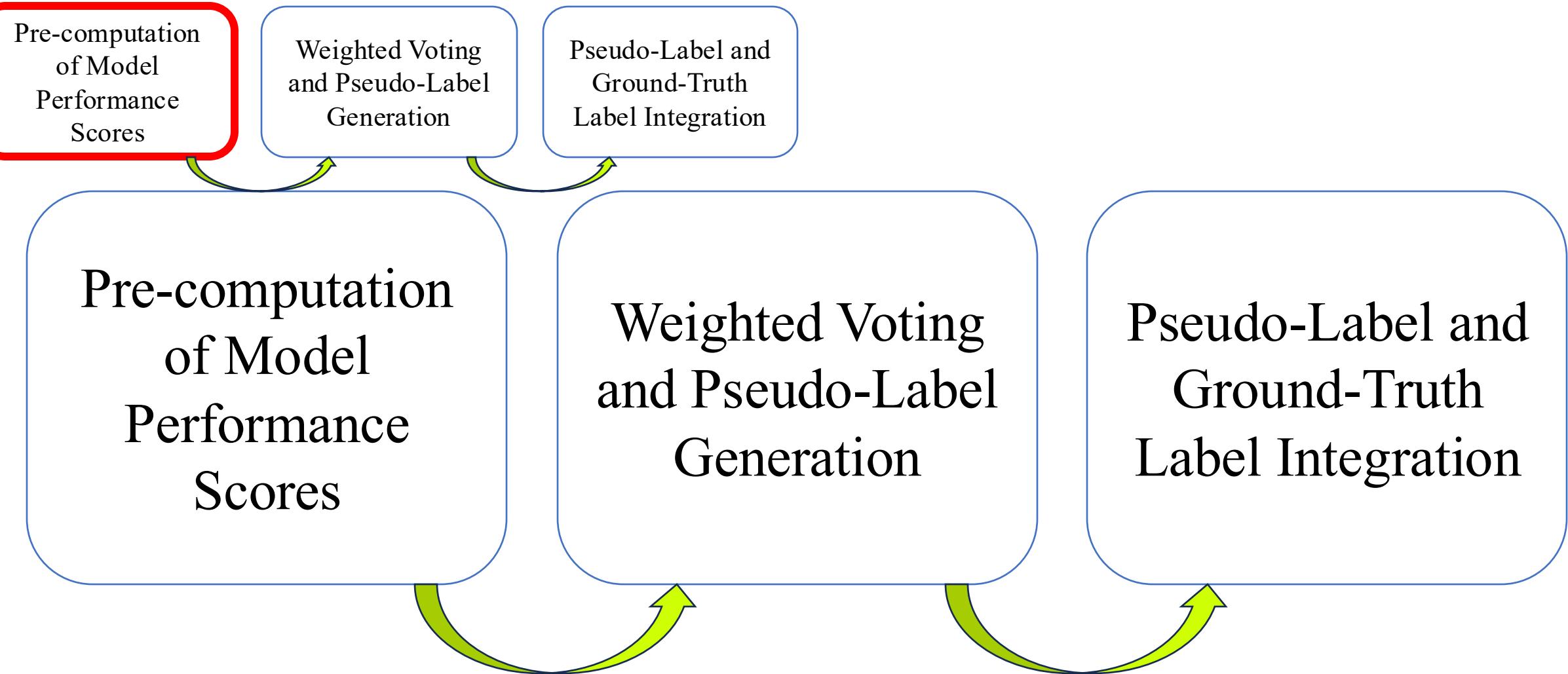
Reference

- [1] Bousselham, W., Thibault, G., Pagano, L., Machireddy, A., Gray, J., Chang, Y.H., Song, X.: Efficient self-ensemble for semantic segmentation. In: Proceedings of the British Machine Vision Conference (BMVC) (2022), <https://bmvc2022.mpi-inf.mpg.de/0892.pdf>
- [2] Caesar, H., Bankiti, V., Lang, A.H., Vora, S., Liong, V.E., Xu, Q., Krishnan, A., Pan, Y., Baldan, G., Beijbom, O.: nuScenes: A Multimodal Dataset for Autonomous Driving . In: Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR). pp. 11618–11628 (Jun 2020). <https://doi.org/10.1109/CVPR42600.2020.01164>
- [3] Cordts, M., Omran, M., Ramos, S., Rehfeld, T., Enzweiler, M., Benenson, R., Franke, U., Roth, S., Schiele, B.: The Cityscapes Dataset for Semantic Urban Scene Understanding . In: Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition (CVPR). pp. 3213–3223 (Jun 2016). <https://doi.org/10.1109/CVPR.2016.350>
- [4] Dietterich, T.G.: Ensemble methods in machine learning. Multiple classifier systems (MCS) pp. 1–15 (2000)
- [5] Geiger, A., Lenz, P., Urtasun, R.: Are we ready for autonomous driving? the kitti vision benchmark suite. In: Proceedings of the IEEE Conference on Computer Vision and Pattern Recognition (CVPR). pp. 3354–3361 (2012). <https://doi.org/10.1109/CVPR.2012.6248074>
- [6] Kirillov, A., Mintun, E., Ravi, N., Mao, H., Rolland, C., Gustafson, L., Xiao, T., Whitehead, S., Berg, A.C., Lo, W.Y., Dollár, P., Girshick, R.: Segment anything (2023), <https://arxiv.org/abs/2304.02643>

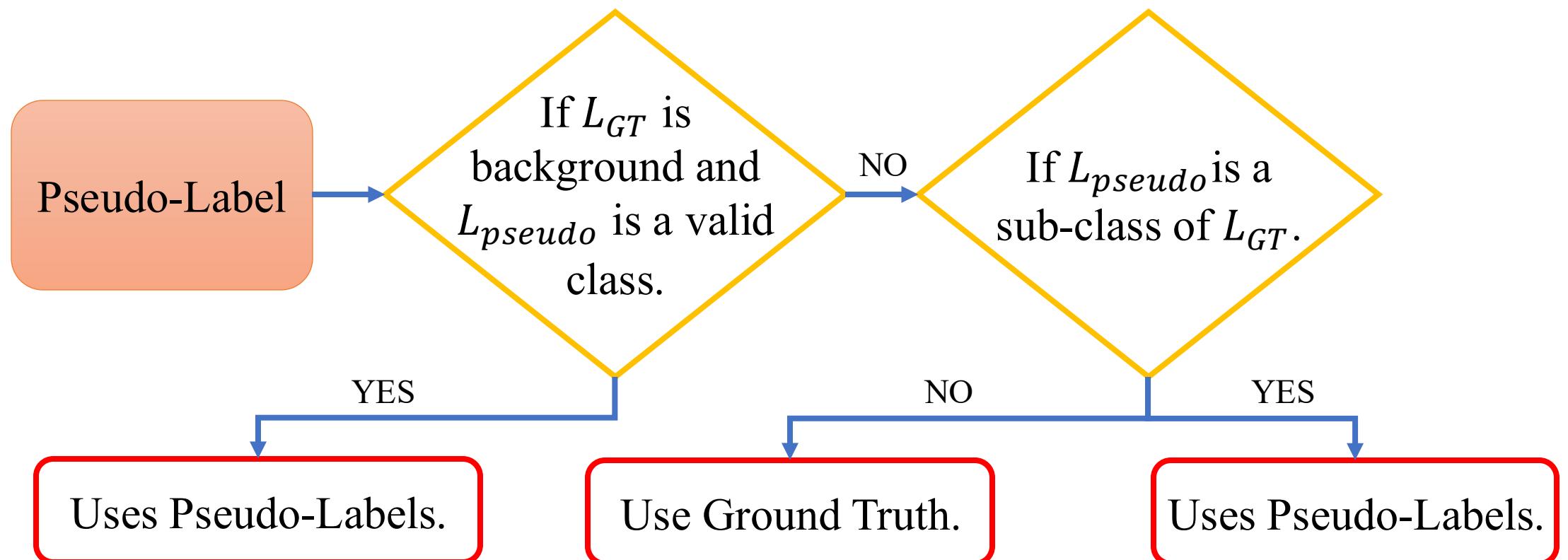
- [7] Lee, D.H.: Pseudo-label : The simple and efficient semi-supervised learning method for deep neural networks. ICML 2013 Workshop : Challenges in Representation Learning (WREPL) (07 2013)
- [8] Niu, H., Hu, J., Lin, J., Jiang, G., Zhang, S.: Eov-seg: Efficient open-vocabulary panoptic segmentation (2024), <https://arxiv.org/abs/2412.08628>
- [9] Xie, Q., Dai, Z., Hovy, E., Luong, T., Le, Q.: Unsupervised data augmentation for consistency training. In: Advances in Neural Information Processing Systems. vol. 33, pp. 6256–6268 (2020), https://proceedings.neurips.cc/paper_files/paper/2020/file/44feb0096faa8326192570788b38c1d1-Paper.pdf
- [10] Yu, F., Chen, H., Wang, X., Xian, W., Chen, Y., Liu, F., Madhavan, V., Darrell, T.: Bdd100k: A diverse driving dataset for heterogeneous multitask learning. In: Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR). pp. 2636–2645 (June 2020)
- [11] Zhang, H., Li, F., Zou, X., Liu, S., Li, C., Yang, J., Zhang, L.: A Simple Framework for Open-Vocabulary Segmentation and Detection . In: Proceedings of the IEEE/CVF International Conference on Computer Vision (ICCV). pp. 1020–1031 (Oct 2023). <https://doi.org/10.1109/ICCV51070.2023.00100>
- [12] Zhang, Y., Jiao, R., Liao, Q., Li, D., Zhang, J.: Uncertainty-guided mutual consistency learning for semi-supervised medical image segmentation. Artificial Intelligence in Medicine 138, 102476 (2023). <https://doi.org/https://doi.org/10.1016/j.artmed.2022.102476>

Thank you for listening!

Integrated Pseudo-Labeling (IPL) Pipeline



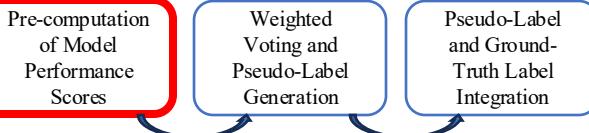
Pseudo-Label and Ground-Truth Label Integration



To expand and **fill in missing annotations** in the original data.

Ensures the **integrity** of the **original high-quality** labels is maintained.

Uses pre-defined R_{manual} to **retain finer granularity** in the final label map.



Pre-computation - Implementation

